Model name		T6
Model namber		T6-602S
Payload (Load) ^{*1}	Rated	2 kg
	Max.	6 kg
Arm length (Joints #1+#2)		600 mm
Repeatability	Joint#1~2	± 0.04 mm
	Joint#3	± 0.02 mm
	Joint#4	± 0.02 deg
Standard cycle time*2		0.49 sec
Max. motion range	Joint#1	± 132 deg
	Joint#2	± 150 deg
	Joint#3	200 mm
	Joint#4	± 360 deg
Max. operation speed	Joint#1-2	4180 mm/s
	Joint#3	1000 mm/s
	Joint#4	1800 deg/s
Join#4 allowable moment of inertia ^{*3}	Rated	0.01 kg⋅m²
	Max.	0.08 kg·m²
Joint #3 down force		83N
Mounting type		Table Top
Installation Environment		Standerd
Weight (cables not included)		22 kg
Applicable Controller		Built in controller
Power / cable length		AC100-240V / 5m
Power Consumption ^{*4}		1.2 kVA
Installed wire for customer use		Hand I/O: IN6/OUT4(D-sub 15pin), User I/O:IN18/OUT12
Installed pneumatic tube for customer use		ø6 mm x 2, ø4mm x 1 : 0.59 MPa (6 kgf/cm ² : 86 psi)
Safety standard		CE mark

Fieldbus I/O (master) PROFIBUS-DP, DeviceNet, EtherNet/IP I/O Cable kit Vision option PV1, CV2 Force sensor option S250 Drive unit (DU)

^{*4 :} It depends on operating environment and operation program.

Supported software option	
Vision Guide 7.0 (CV2/CV1/PV1)	•
RC+ API 7.0	•
ECP	•
GUI Builder 7.0	•
OCR	•
Supported controller option	
Teaching pendant TP1	-
TP2	•
TP3	•
Conveyor tracking	-
PG motion system	-
Emergency stop switch	•
RS-232C cards	-
I/O expansion cards	-
Fieldbus I/O (slave)	
PROFIBUS-DP, DeviceNet, CC-Link,	•
EtherNet/IP, PROFINET, EtherCAT	

^{*1 :} Do not apply the load exceeding the maximum payload.
*2 : Cycle time based on round-trip arch motion (300mm horizontal, 25mm vertical) with 2 kg payload (path coordinates optimized for maximum speed).
*3 : If the center of gravity is at the center of each arm, set the eccentric quantity using INERTIA